

Que peut-on faire *exactement*, avec l'algèbre linéaire flottante

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M2RMA Calcul Exact
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Outline

1 Numerical linear algebra: the BLAS

- Why ?
- BLAS
- Optimizations

2 FFLAS: a BLAS for finite fields

- Delayed reductions
- Cache tuning
- Sub-cubic algorithm
- Memory efficiency

Why ?

Huge range of applications in numerical computations

- All PDE based computations: Weather forecasts, mechanical designs, computational chemistry, ...
- ODE, Control, ...

boil down to linear algebra efficiency.

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⇒ design for long term optimizations and portability ?

BLAS : Basic Linear Algebra Subroutines

- 1979 [Lawson & Al.], first set of Fortran subroutines
- 1988 [Dongarra & Al], level 2 (MatVect)
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Optimized implementations :

- machine specific by computer vendors (Intel, SGI, IBM, ...)
- architecture independent: ATLAS, GOTO.

Features

- 4 data types : float (s), double (d), complex (c), double cpx (z)
- 3 levels :
 - level 1 Vector ops (rotation, dot-prod, add, scal axpy,...)
 - level 2 Matrix-Vector ops (MatVect prod, triangular system solve, tensor product,...)
 - level 3 Matrix-Matrix ops (MatMul, multi triangular system solve,...)

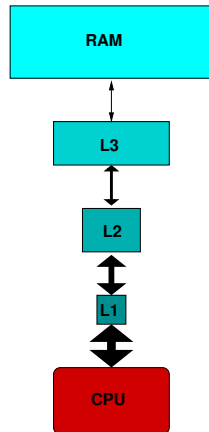
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Optimizing data locality

Memory considerations:

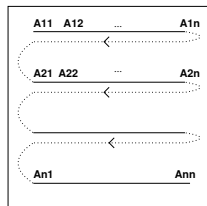
- **CPU-Memory communication:** bandwidth gap
⇒ Hierarchy of several cache memory levels



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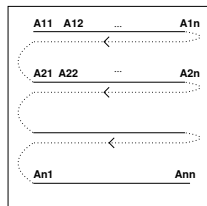
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- CPU-Memory communication: bandwidth gap
⇒ Hierarchy of several cache memory levels
- Row major representation of matrices
- a RAM memory access can fetch a bunch of **contiguous** elements



Optimizing data locality

Comparing

```
for i=1 to n do  
  for j=1 to n do  
    for k=1 to n do  
       $C_{i,j} \leftarrow C_{i,j} + A_{i,k}B_{k,j}$   
    end for  
  end for  
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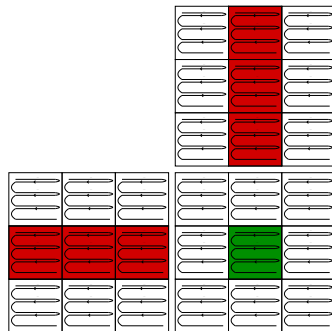
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Further memory optimizations

Larger dimensions: cache blocking.

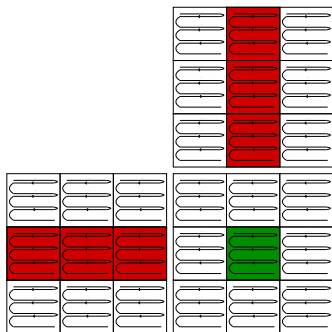
⇒ split matrices into blocks, s.t. their product can be computed within the cache.



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Reuse of the data

- if $\text{Work} \gg \text{Data}$: memory fetch is amortized
⇒ reach the peak performance of the CPU
- Matrix multiplication: $n^3 \gg n^2$
⇒ well suited for block design

Arithmetic optimizations

- fma (fused multiply and accumulate) $z \leftarrow z + x * y$
- SSE: 128 bits registers
- pipeline
- ...

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Tends to give advantage to floating point arithmetic up to now.

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Overview

- word sized finite fields : elements can be represented on 16, 23, 32, 53 or 64 bits
- Delayed modular reductions : avoid unnecessary field arithmetic by computing over \mathbb{Z} as much as possible.
- Cache tuning
- Fast sub-cubic algorithm

Delayed reductions

Existence of 2 ring homomorphisms :

- $\Phi : GF(q) \rightarrow \mathbb{Z}$

- $\Psi : \mathbb{Z} \rightarrow GF(q)$

$$GF(q) \xrightarrow{\Phi} \mathbb{Z}$$

s.t. $\begin{array}{ccc} \downarrow +_{GF(q)}, \times_{GF(q)} & & \downarrow +_{\mathbb{Z}}, \times_{\mathbb{Z}} \\ & & \end{array}$ commutes

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$$GF(q) \xleftarrow{\Psi} \mathbb{Z}$$

$$\mathbb{Z}_p : \Phi = Id, \Psi : x \rightarrow x \pmod p$$

$$GF(p^k) : \Phi : P(X) \rightarrow P(\gamma) \text{ with } \gamma > nk(p - 1). \text{ (}\gamma\text{-adic reconstruction).}$$

Delayed reductions

⇒ compute over \mathbb{Z} with word size elements (int, long, float double)

⇒ perform the necessary back conversion (Ψ) only when necessary.

Conditions of validity :

$$\mathbb{Z}_p : n(p-1)^2 < 2^m$$

$$GF(p^k) : q(2k-1) < 2^m \text{ and } \gamma > nk(p-1).$$

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Could mimic the numerical BLAS.

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Instead :

**Reuse the existing technology: compute with floating points
and use BLAS.**

Pros:

- floating point arithmetic is better optimized
- long term efficiency: rely on the numerical community

Cons:

- exponent is useless
- integer arithmetic may become as efficient

Strassen-Winograd algorithm

$$\begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix},$$

- 8 additions:

$$\begin{array}{ll} S_1 \leftarrow A_{21} + A_{22} & T_1 \leftarrow B_{12} - B_{11} \\ S_2 \leftarrow S_1 - A_{11} & T_2 \leftarrow B_{22} - T_1 \\ S_3 \leftarrow A_{11} - A_{21} & T_3 \leftarrow B_{22} - B_{12} \\ S_4 \leftarrow A_{12} - S_2 & T_4 \leftarrow T_2 - B_{21} \end{array}$$

- 7 recursive multiplications:

$$\begin{array}{ll} P_1 \leftarrow A_{11} \times B_{11} & P_5 \leftarrow S_1 \times T_1 \\ P_2 \leftarrow A_{12} \times B_{21} & P_6 \leftarrow S_2 \times T_2 \\ P_3 \leftarrow S_4 \times B_{22} & P_7 \leftarrow S_3 \times T_3 \\ P_4 \leftarrow A_{22} \times T_4 & \end{array}$$

- 7 final additions:

$$\begin{array}{ll} U_1 \leftarrow P_1 + P_2 & U_5 \leftarrow U_4 + P_3 \\ U_2 \leftarrow P_1 + P_6 & U_6 \leftarrow U_3 - P_4 \\ U_3 \leftarrow U_2 + P_7 & U_7 \leftarrow U_3 + P_5 \\ U_4 \leftarrow U_2 + P_5 & \end{array}$$

- The result is the matrix:

$$C = \begin{bmatrix} U_1 & U_5 \\ U_6 & U_7 \end{bmatrix}$$

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Over finite fields : not problem

- update the validity condition for delayed reductions from

$$k(p-1)^2 < 2^{53}$$

to

$$\left(\frac{1+3^l}{2}\right)^2 \lceil \frac{k}{2^l} \rceil (p-1)^2 < 2^{53} \text{ for } l \text{ recursive levels.}$$

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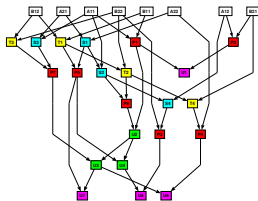
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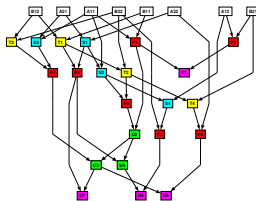
Cons:

- more reductions if q or n is big
- temporary memory allocations

Memory requirements of Winograd's algorithm

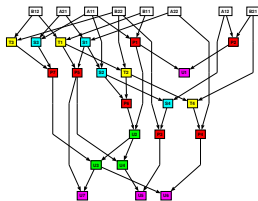


Memory requirements of Winograd's algorithm



- $C \leftarrow A \times B + C \Rightarrow$ from 3 to 2 temp. (3 pre-adds)
- $C \leftarrow A \times B + C \Rightarrow$ from 3 to 2 temp. (2 pre-adds, overwriting inputs)
- $C \leftarrow A \times B$ **fully in-place** (overwriting inputs)

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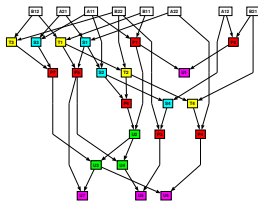


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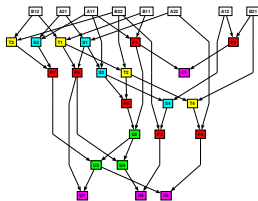
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\Rightarrow **yes** $7.2n^{2.807}$ instead of $6n^{2.807}$