

Make Things Talk With Arduino



Didier Donsez

Université Joseph Fourier
PolyTech'Grenoble LIG/ADELE

`Didier.Donsez@imag.fr`

`Didier.Donsez@ieee.org`

Motivations

- Physical computing
 - Create interactive objects or environments.
 - for artists, designers, hobbyists
- Fast prototyping
 - Mockup, proof of concept, DIY
- Education
 - Teach/learn electronic and programming for dummies
 - teachers, high school
- Free and open-source software and hardware
 - Board designs, Tools chain, Programs ...
 - but silicium and PCB can not be downloaded like FOSS

Community (TBD)

- Blog, Playground, Forum
- How-to
- Multi-languages
- Popularity
- Contributes !
 - Register and Q&A, translate, explain ... !

Hardware

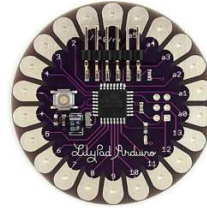
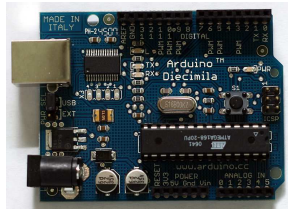
- Board
 - Microcontroller Atmel AVR (8 bits, 8-16Mhz)
 - ATmega8, ATmega168, ATmega328, and ATmega1280.
 - 16 to 128 KB flash
 - 1KB to 8KB SRAM,
 - 0.5 to 4 KB EEPROM)
 - Analogic Inputs
 - 6 pour 328, ?? for Mega2560
 - Digital IO and PWM
 - 14 (6 are PWM) for 328, ?? for Mega2560
 - Extension Catalog
 - Communications: RS-232, USB, Ethernet, BT, XBee
 - Sensors
 - Actuators (servo moteurs, ...)
 - Several form factors : nano, ...
 - and Shields
- Low cost
 - Start from 20€ (even 5€ if recycling)
 - Several manufacturers and dealers
 - Licence LGPL
 - But « **Arduino** » is only allow for official products

Form factors

■ Boards

■ Official

- USB
- Mega
- Pro
- Mini & Nano
- LilyPad (wearable)



■ Clones

- Freeduino, Seeeduino Stalker, Funnel IO, BlackWidow ...
- Erzats (Cortex M3, ...)
 - FEZ Panda, Netduino, Leaf Maple



■ *Piggy-backed* Shields

- Ethernet
- Bluetooth
- XBee
- Pilot



- solderless breadboards ...



Programming Languages

- Wiring
 - based on Processing <http://processing.org/>
 - C/C++ like syntax
- C/C++
 - GNU chain
- AMForth (ATMega Forth)
 - <http://amforth.sourceforge.net>
- AVR Assembly
 - WinAVR, AVRDUDE
- Graphical box tool
 - for artists

Syntax (i)

- Program structure

- `void setup() { ... } void loop() { ... }`

- Statements

- `;` `{ }`

- `//` `/* */`

- `#define` `#include`

- Control structures

- `if`, `if...else`, `for`, `switch case`, `while`,
`do... while`

- `break`, `continue`, `return`, `goto`

- Control structures

- `type func(type param, ...)`

Syntax (ii)

■ Data Types

- `void, boolean, char, unsigned char, byte,`
- `int, unsigned int, word, long, unsigned long`
- `float, double, string (char[])`

■ Contructor

- `[]`

■ Variables

- `local, global, static local, volatile, const`
- `sizeof()`

■ Operators

- Arithmetic = `+, -, *, /, %`
- Comparison = `==, !=, <, >, <=, >=`
- Boolean `&&, ||, !`
- Bitwise `&, |, ^, ~, <<, >>`
- Pointer Access `*, &`
- Compound `==, --, +=, -=, *=, /=, &=, |=`

Interruptions

- Motivation : avoid polling (with complex timing calibration)
- External interruptions
 - Digital pin 2 and 3 on Arduino
 - + digital pin 21, 20,19,18 on Mega
 - `attachInterrupt(interrupt, funct, mode)`, `detachInterrupt(funct)`
 - *mode* = *LOW*, *CHANGE*, *RISING*, *FALLING*
- Critical section
 - `noInterrupts(); ... interrupts();`
- Example

```
#define LED 13;
volatile int state = LOW;
void setup() {
  pinMode(LED, OUTPUT);
  attachInterrupt(0, blink, CHANGE);
}
void loop() { digitalWrite(LED, state); }
void blink() { state = !state; }
```

Code snippet

Blink

// blink.pde

`#define LED_PIN 13`

// run once at the start of a program which can be used for initializing settings

`void setup () {`

`pinMode (LED_PIN, OUTPUT); // enable pin 13 for digital output`
`}`

// called repeatedly until the board is powered off

`void loop () {`

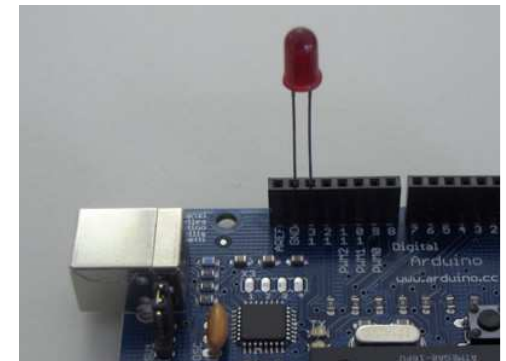
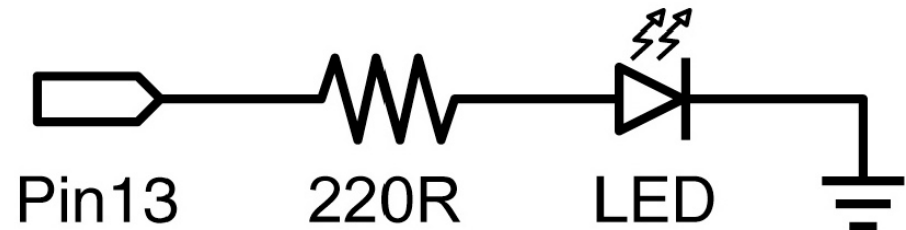
`digitalWrite (LED_PIN, HIGH); // turn on the LED`

`delay (1000); // wait one second (1000 milliseconds)`

`digitalWrite (LED_PIN, LOW); // turn off the LED`

`delay (1000); // wait one second`

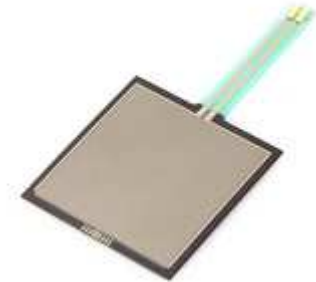
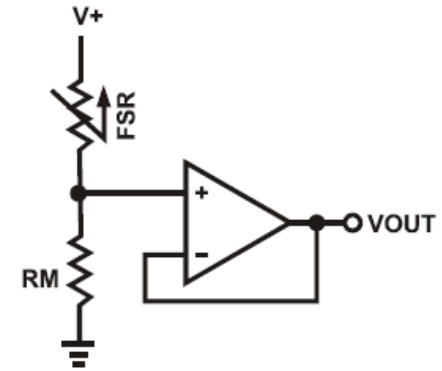
`}`



Code snippet for input Weight

■ Application : wiifit, i-shoe, i-sofa ...

```
void setup() { Serial.begin(9600); }  
void loop() {  
  // read the analog input into a variable:  
  int analogValue = analogRead(0);  
  Serial.println(analogValue);  
  delay(10);  
}
```



Code snippet for I2C Input and Control

Nunchuck → Servo motor

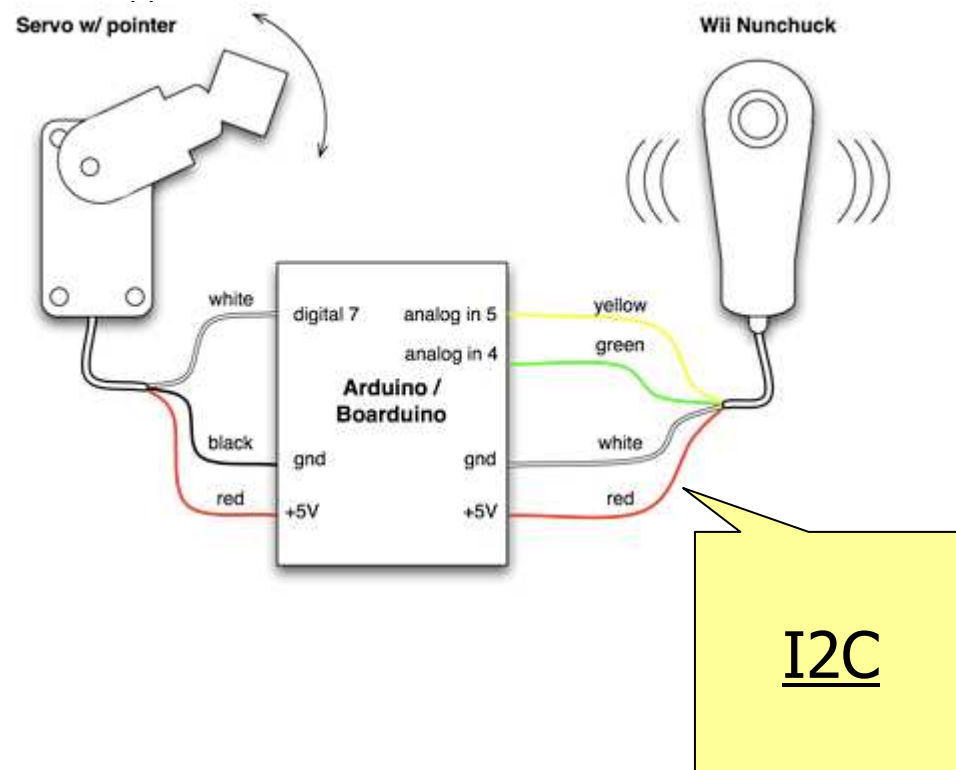
```
#include <Wire.h>
#include "nunchuck_funcs.h"
#include <Servo.h>
```

```
Servo myservo;
byte joyx,prevjoyx, zbut,cbut;
prevjoyx=0; // global
```

```
void setup() {
  myservo.attach(9); // attaches the servo on pin 9 to th
  nunchuck_setpowerpins();
  nunchuck_init(); // send the initialization handshake
}
```

```
void loop() {
  nunchuck_get_data();
  joyx = nunchuck_joyx();
  zbut = nunchuck_zbutton();
  cbut = nunchuck_cbutton();

  if(zbut==1) {
    myservo.write(0); delay(500);
  } else if(zbut==1) {
    myservo.write(180); delay(500);
  } else if((prevjoyx+5<joyx) || (joyx<prevjoyx-5)) {
    prevjoyx=joyx;
    myservo.write(joyx+90); delay(100);
  } else { delay(100); }
}
```



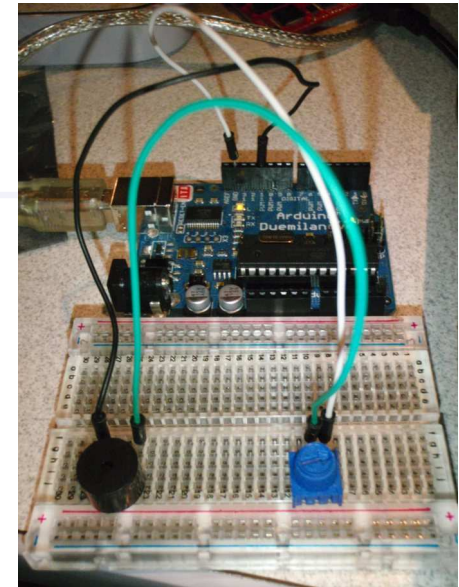
Code snippet for PWM Music maestro !

```
// from Tom Igoe
#include "pitches.h"
#define PIN 8
int melody[] = { NOTE_C4 /* 262 Hz */, NOTE_G3,
  NOTE_G3, NOTE_A3, NOTE_G3, 0, NOTE_B3, NOTE_C4};
int noteDurations[] = { 4,8,8,4,4,4,4,4 };

void setup() { }

void playMelody() {
  for (int thisNote = 0; thisNote < 8; thisNote++) {
    int noteDuration = 1000/noteDurations[thisNote];
    tone(PIN, melody[thisNote],noteDuration);
    int pauseBetweenNotes = noteDuration * 1.30;
    delay(pauseBetweenNotes);
  }
}

void playMelody() {
  play(); delay(2000);
}
```



Communications

- Talking to the Cloud, Internet of Things
- Serial: RS232, I2C, 1-Wire
- Ethernet
- WiFi
- Bluetooth
- ZigBee (XBee) 900 MHz, 2.4GHz
- RF 433MHz
- IrDA

Host

- RXTX.org
- processing.serial

```
import processing.serial.*;
import cc.arduino.*;
Arduino arduino;
int ledPin = 13;
void setup() {
  //println(Arduino.list());
  arduino = new Arduino(this, Arduino.list()[0], 57600);
  arduino.pinMode(ledPin, Arduino.OUTPUT);
}
void draw() {
  arduino.digitalWrite(ledPin, Arduino.HIGH);
  delay(1000);
  arduino.digitalWrite(ledPin, Arduino.LOW);
  delay(1000);
}
```

- Eclipse Terminal plugin
- Putty

Tools



- **Arduino IDE**
 - <http://arduino.cc/en/Main/Software>
 - basic but quick startup
 - Portable (Java app)
 - based on Processing
- **Eclipse IDE CDE (C/C++)**
 - + AVR plugin + RXTX plugin
 - <http://www.arduino.cc/playground/Code/Eclipse>
 - More complex
- **Emulators**
 - Virtual Breadboard
- Remote management ??
- Unit testing
- Command lines
 - <http://www.arduino.cc/playground/Code/WindowsCommandLine>
- **Builder (cmake, ant, maven)**
 - <http://www.arduino.cc/playground/Main/DevelopmentTools>

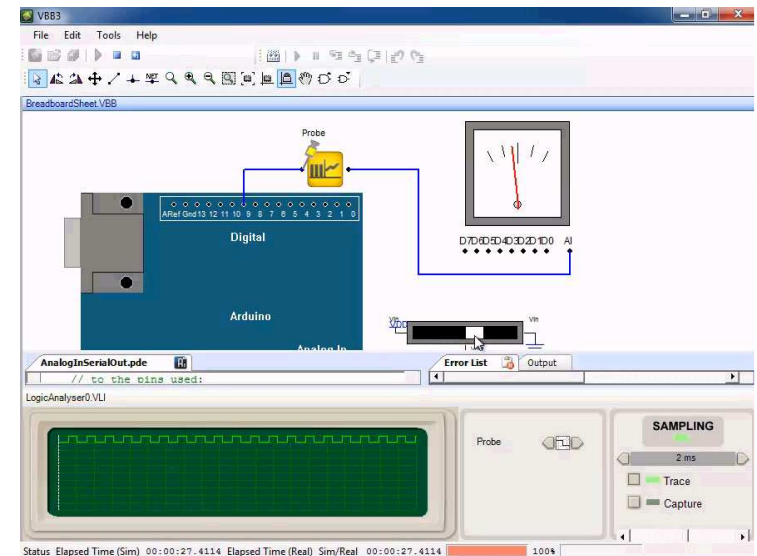
A screenshot of the Arduino IDE window titled "Blink | Arduino 0018". The menu bar includes File, Edit, Sketch, Tools, and Help. The toolbar shows icons for running, saving, opening, and other sketch operations. The main text area displays the code for the "Blink" sketch in a monospaced font. The code defines LED_PIN as 13 and contains setup and loop functions that toggle the LED state with 1000ms delays. The status bar at the bottom shows the line number 18.

```
// Blink.pde

#define LED_PIN 13

// run once at the start of a program which can be used for initializing settings
void setup() {
  pinMode(LED_PIN, OUTPUT); // enable pin 13 for digital output
}

// called repeatedly until the board is powered off
void loop() {
  digitalWrite(LED_PIN, HIGH); // turn on the LED
  delay(1000); // wait one second (1000 milliseconds)
  digitalWrite(LED_PIN, LOW); // turn off the LED
  delay(1000); // wait one second
}
```



Arduino + Eclipse

```
#include <HardwareSerial.h>
#include <WProgram.h>
#include <wiring.h>
#include <WConstants.h>
#include <binary.h>
#include <pins_arduino.h>
#include <wiring_private.h>

int main(void) {

    /* Must call init for arduino to work properly */
    init();

    /******
    /* Add your setup code here */
    /******

    for (;;) {

        /******
        /* write main loop here */
        /******

    } // end for

    // you-MUST-NEVER-return-from-main

} // end main
```

- Wiring

- <http://wiring.org.co>
- <http://www.processing.org>

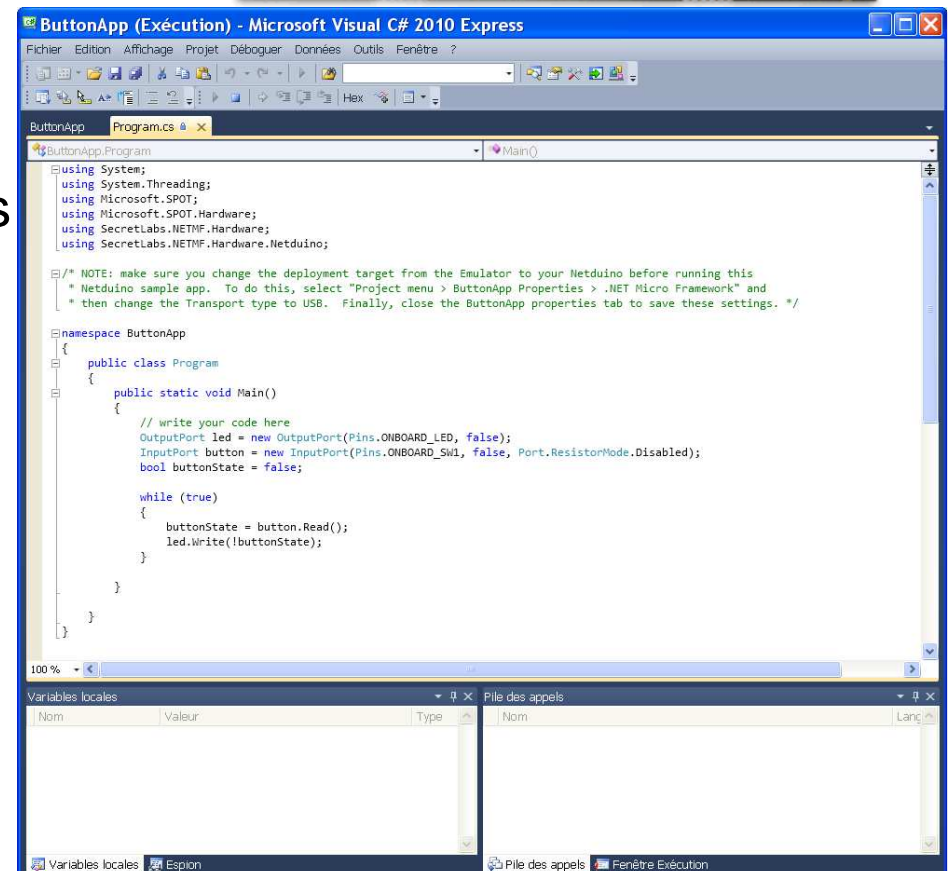
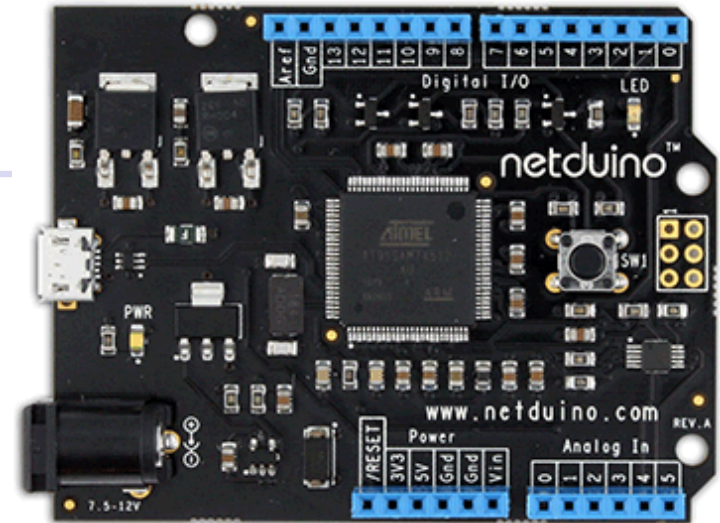
Erzats

- Arduino pin compatible → Shield compatibility
- But powerful processors
 - Netduino (<http://netduino.com>)
 - Leaf Maple <http://leaflabs.com/docs/maple/>
 - FEZ (<http://www.tinyclr.com>)

Netduino

<http://netduino.com>

- Atmel ARM7 48MHz
 - Code Storage: 128 KB
 - RAM: 60 KB
 - 20 GPIOs with SPI, I2C
 - 2 UARTs (1 RTS/CTS)
 - 4 PWM and 6 ADC channels
 - Compliant with Arduino shields
- Netduino Plus
 - + Micro SD + Ethernet
- Development
 - .NET Micro Framework C#
 - Visual Studio Express
 - SharpDevelop ???



FEZ

<http://www.tinyclr.com>

■ FEZ Panda

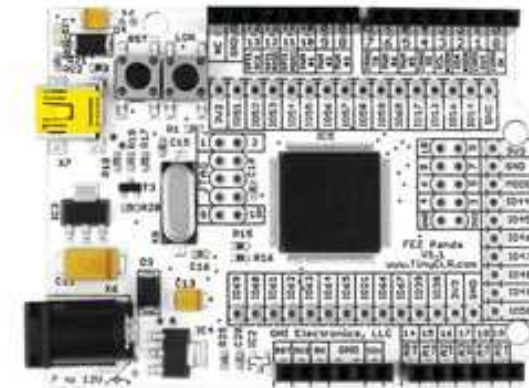
- 72Mhz NXP ARM processor, 62KB RAM, 148KB FlashRAM
- 60 PIN (6PWM, 4TTL UART, SPI, I2C, CAN, OneWire)
- JTAG exposed, USB Client

■ FEZ Domino

- 72Mhz NXP ARM processor, 62KB RAM, 148KB FlashRAM
- 30 PIN (6PWM, 3TTL UART, SPI, I2C, CAN, OneWire)
- USB Host & Client, RTC, micro SD connector

■ Dev tools

- C# .NET MF
- VisualStudio



WaspMote

<http://www.libelium.com/products/waspmote/hardware>

■ Hardware

- ATmega1281 8MHz
- 8KB SRAM 4KB EEPROM 128KB FLASH
- SD Card, XBee Socket
- RTC (32KHz)
- 7 Analog, 8 Digital (I / O), 1 PWM, 2 UARTs, 1 I2C, 1USB
- On board sensors: Temperature, Accelerometer: $\pm 2g$ / $\pm 6g$
- Battery and Solar panel slots. 3V CR2032 auxiliary battery
- **Not compatible with Arduino shields**

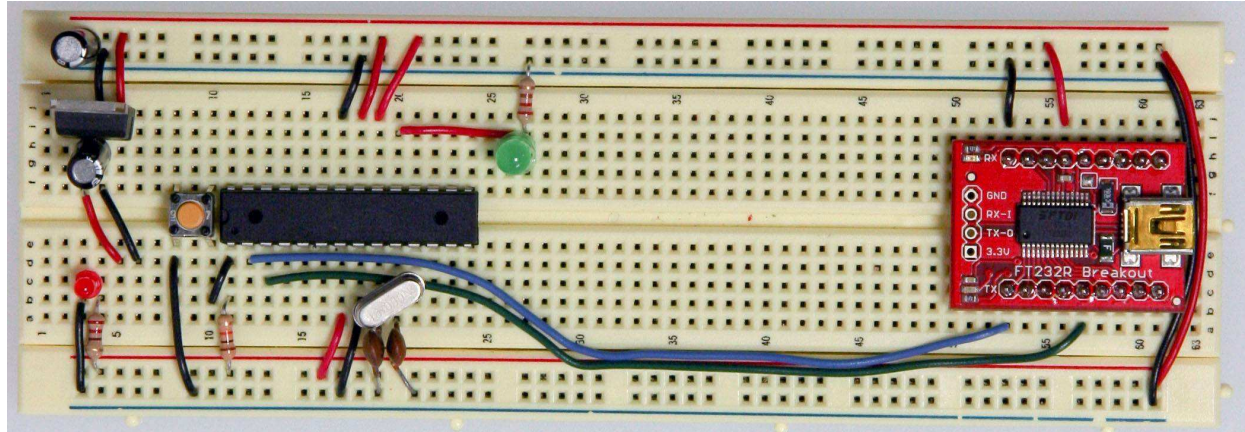
■ Software

- **Wiring**
- FOSS API

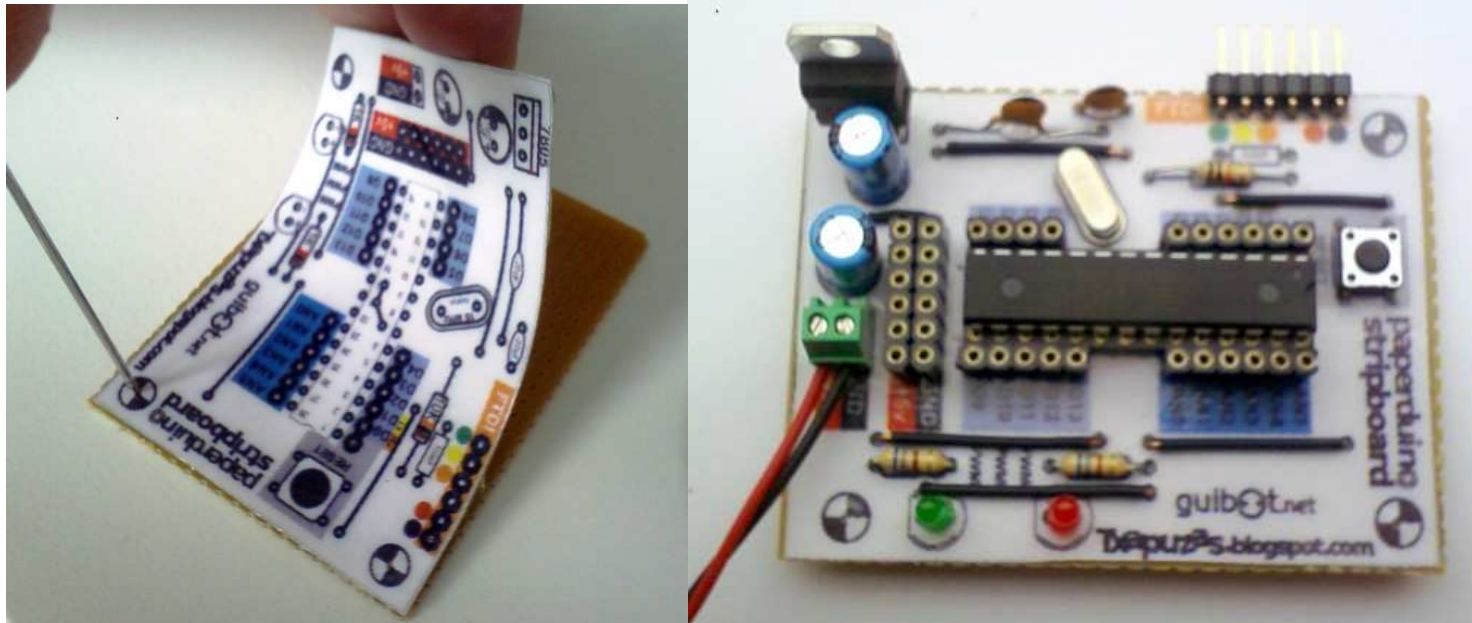


Homebrew Arduino

- BreadDuino



- Paperduino (stripboard, perfboard)



Books

- Banzi, Massimo (March 24, 2009). Getting Started with Arduino (1st ed.). Make Books. pp. 128. ISBN 0596155514.
<http://www.makershed.com/ProductDetails.asp?ProductCode=9780596155513>.
- Tom Igoe, Making Things Talk: Practical Methods for Connecting Physical Objects, Make Books , 2007, ISBN-10: 0596510519
- Osher, Jonathan; Blemings, Hugh (December 28, 2009). Practical Arduino: Cool Projects for Open Source Hardware (1st ed.). Apress. pp. 500. ISBN 1430224770. <http://www.apress.com/book/view/9781430224778>.
- Noble, Joshua (July 15, 2009). Programming Interactivity: A Designer's Guide to Processing, Arduino, and openFrameworks (1st ed.). O'Reilly Media. pp. 768. ISBN 0596154143. <http://oreilly.com/catalog/9780596800581/>.
- Schmidt, Maik (November 20, 2010). Arduino: A Quick-Start Guide (1st ed.). The Pragmatic Bookshelf. pp. 275. ISBN 978-1-93435-666-1.
<http://pragprog.com/titles/msard/arduino>.
- Sparkfun Inventor'Guide
 - <http://www.sparkfun.com/tutorial/AIK/CIRC00-sheet-SPAR.pdf>
 - <http://www.sparkfun.com/tutorial/AIK/ARDX-EG-SPAR-PRINT-85.pdf>

Shops

- Lectronix.fr
- Farnell.fr
- Radiospare.fr

- Sparkfun.com
- Seedstudio.com
- CoolComponent.co.uk

- eBay

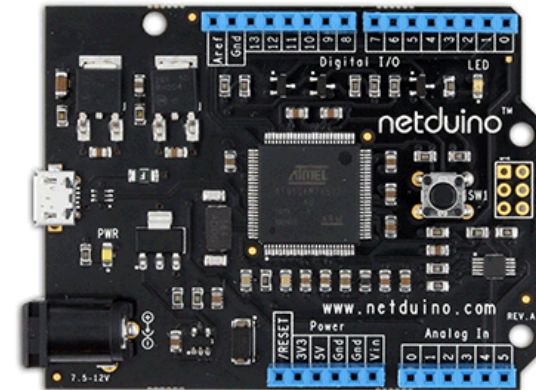
And Now !

The Exercises

- Choose one in the Sparkfun Inventor'Guide
 - <http://www.sparkfun.com/tutorial/AIK/CIRC00-sheet-SPAR.pdf>
 - <http://www.sparkfun.com/tutorial/AIK/ARDX-EG-SPAR-PRINT-85.pdf>

Bonus track

Personal Collection



Video Game Shield

Personal DIY projects

- Wattmeter
- Plant
- Arcade joystick

Polytech'Grenoble projects